



Who we are

A multidisciplinary start-up team rooted in IIT's Event-Driven Perception for Robotics group, including mechanical and electrical engineering, software dev, neural networks and information theory.

What we do

We are designing bioinspired, asynchronous, efficient, high density and low latency touch sensors with neuromorphic edge computing capability.

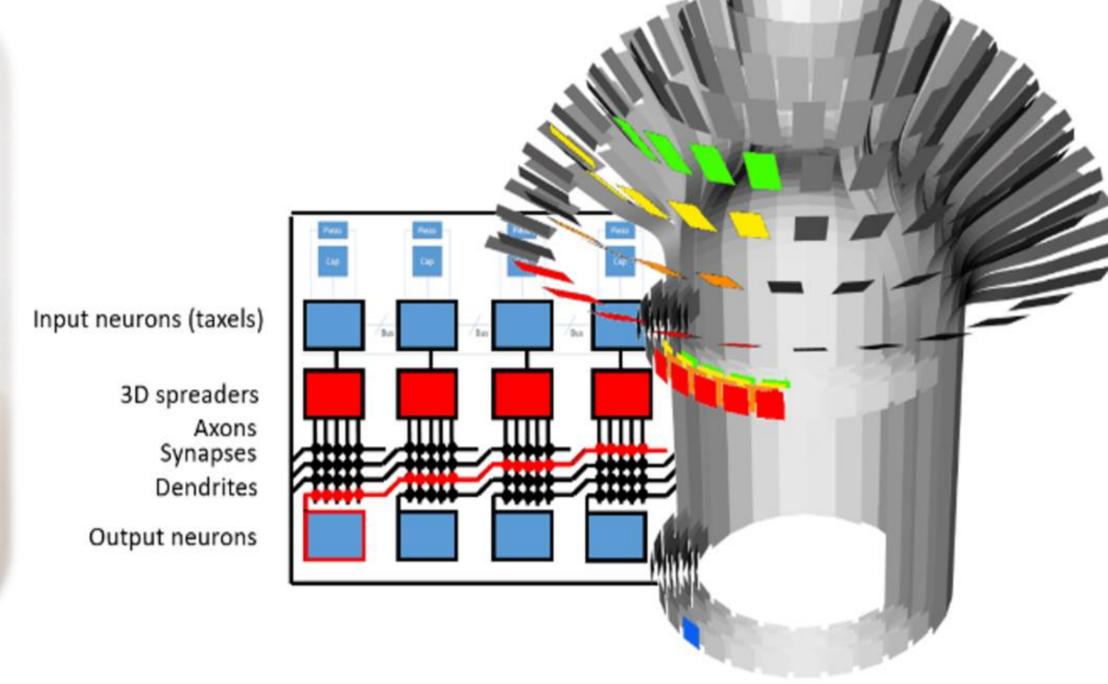
Why us

We target sustainable, bio-degradable sensors from European supply chain, with sensor-processor-actuator integration, to create printable nervous systems.

Simon F. Müller-Cleve, Simeon A. Bamford*, Chiara Bartolozzi

Printable, Flexible Artificial 3D Spiking Neural Networks

Sensor placement Seusor placement



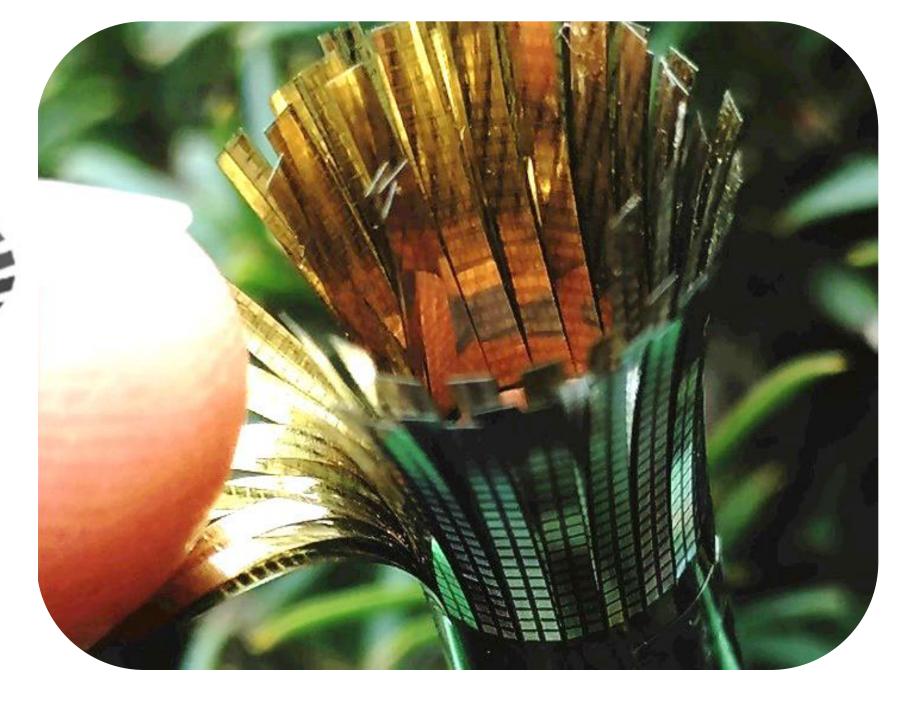


Fig1: (left) assembled dummy sensor (polyimide with silicon spacers) incl. space for spiking neural network (SNN); (center) sensor placement and network infrastructure; (right) photolithographically patterned inorganic transistors.

Spiking Neural Network

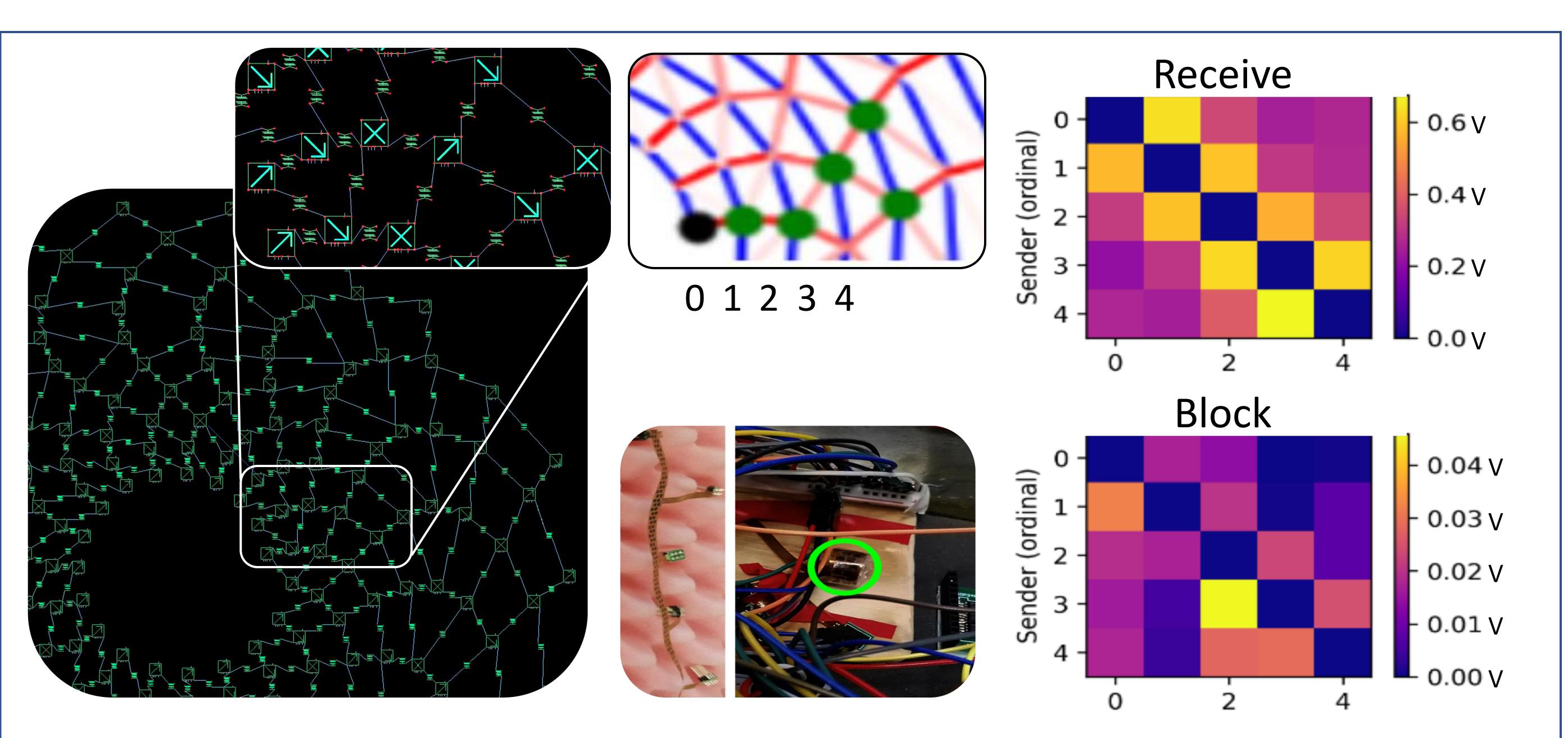


Fig2: (left) simulated topology of SNN connections across coiled layers via capacitors, with nodes programmed alternately as senders (\nearrow), receivers (\searrow) and blockers (X); (centre-top) possible axonal pathways formed starting from two neurons at central layer; (centre-bottom) metal-only prototype to test pulsed transmission between coiled layers; (right) heat map of signal strength when sending a pulse from plate and measuring the response at all other plates in a stack, (with ordinal layer numbering following centre-top), suggesting the possibility to create specific axonal pathways.



